

## S P E C I F I C A T I O N

BE IT KNOWN THAT I, TOSHIFUMI SUGISAWA residing at  
c/o Sumitomo Rubber Industries, Ltd., 6-9, 3-chome, Wakinohama-cho,  
Chuo-ku, Kobe-shi, Hyogo-ken, Japan, a subject of Japan, have  
invented certain new and useful improvements in

### METHOD AND APPARATUS FOR ALARMING DECREASE IN TIRE AIR-PRESSURE AND PROGRAM FOR ALARMING DECREASE IN TIRE AIR-PRESSURE

of which the following is a specification:-

METHOD AND APPARATUS FOR ALARMING DECREASE IN  
TIRE AIR-PRESSURE AND PROGRAM FOR ALARMING  
DECREASE IN TIRE AIR-PRESSURE

BACKGROUND OF THE INVENTION

The present invention relates to a method and apparatus for alarming decrease in tire air-pressure and a program for alarming decrease in tire air-pressure. More particularly, it relates to a method and apparatus for alarming decrease in tire air-pressure and a program for alarming decrease in tire air-pressure with which it is possible to improve the detection accuracy without issuing an erroneous alarm even in the case where a large driving force is applied when the vehicle is, for instance, running on a climbing road or when it performs trailer towing.

While various methods for detecting decompression of a tire attached to a vehicle have been suggested so far, the applicant of the present invention suggests a method for detecting decompression in which judgment of decrease in air-pressure can be performed by using a "turning correction logic" also during turning movements of the vehicle (see Japanese Unexamined Patent Publications No. 8713/1994 and No. 8714/1994).

According to the methods for detecting decompression as recited in Japanese Unexamined Patent Publications No. 8713/1994 and No. 8714/1994, decompression of a tire is detected upon comparing angular velocity signals from wheel speed sensors attached to each wheel. More particularly, wheel speed sensors composed of gearings provided with a magnetic pickup are employed for measuring respective wheel speed values C1, C2, C3 and C4 of the four wheels, and these

values C1, C2, C3 and C4 are substituted into the following equation (1) for obtaining an error value DEL'.

$$\text{DEL}' = \frac{[(C1 + C4)/2 - (C2 + C3)/2] \times 100}{[(C1 + C2 + C3 + C4)/4]} \quad (1)$$

The error value DEL' is then substituted into the following equation (2) for the "turning correction logic" for obtaining a corrected error value DEL.

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$$\text{DEL} = \text{DEL}' - \text{LAT} \times A(\text{DEL}' - \text{lateral G} \times (\text{correction coefficient 1} + \text{slip rate} \times \text{correction coefficient 2})) \quad (2)$$

15

When it is detected that the corrected value falls within a range of a specified threshold of 0.05 to 0.5, a tire alarm indicator within the vehicle is actuated for indicating that at least one tire has been detected.

20

However, where a large driving force is required, for instance, when running up a steep climb or when performing trailer towing, it would happen that such corrections could not be sufficiently performed particularly in the driving wheels so that erroneous alarm was apt to happen.

25

One possible factor thereof might be that a large slip is generated at the tire upon application of large driving force during turning movements so that corrections cannot be sufficiently performed by the above equation for turning correction alone.

### SUMMARY OF THE INVENTION

The present invention has been made for solving such problems, and it is an object thereof to provide a method and apparatus for alarming decrease in tire air-pressure and a program for alarming  
5 decrease in tire air-pressure with which it is possible to improve the detection accuracy without issuing erroneous alarm even in the case where a large driving force is applied when the vehicle is, for instance, running on a climbing road or when it performs trailer towing.

According to a first aspect of the present invention, there is  
10 provided a method for alarming decrease in tire air-pressure in which decrease in tire air-pressure is determined on the basis of rotational velocity information of a wheel of a vehicle,

wherein respective thresholds for determining whether judgment of decrease in tire air-pressure is to be made or not are  
15 changed depending on magnitude of driving torque of the vehicle when the vehicle is performing turning movements.

According to a second aspect of the present invention, there is provided an apparatus for alarming decrease in tire air-pressure in which decrease in tire air-pressure is determined on the basis of  
20 rotational velocity information of a wheel of a vehicle. The apparatus includes velocity detecting means which detect wheel speeds of the respective tires, a judging means which judges decrease in tire air-pressure on the basis of the wheel speeds detected by the velocity detecting means, and an alarming means which issues an alarm when a  
25 decrease in tire air-pressure is judged in the judging means. The apparatus further includes a threshold changing means which changes respective thresholds for determining whether judgment of decrease in

tire air-pressure is to be made or not depending on magnitude of driving torque of the vehicle when the vehicle is performing turning movements.

It is preferable that the apparatus includes:

an engine torque detecting means which detects an engine  
5 torque of the vehicle,

an engine rotational number detecting means or a shift  
position detecting means which detects an engine rotational number of  
the vehicle, and

a lateral directional acceleration detecting means which  
10 detects a lateral direction acceleration of the vehicle,

wherein a driving force applied onto tires of driving wheels is  
obtained on the basis of the engine torque, the engine rotational number  
or shift position, wheel rotational numbers as calculated from the wheel  
speeds detected by the velocity detecting means, and a tire radius,

15 wherein a turning force applied onto the tires of the driving  
wheels is obtained from the lateral directional acceleration, and

wherein a magnitude of force acting on the driving wheels is  
obtained from the driving force and the turning force.

It is preferable that the apparatus includes:

20 an engine torque detecting means which detects an engine  
torque of the vehicle,

an engine rotational number detecting means or a shift  
position detecting means which detects an engine rotational number of  
the vehicle, and

25 a lateral directional acceleration detecting means which  
detects a lateral directional acceleration of the vehicle,

wherein a driving force applied onto tires of driving wheels is

obtained on the basis of the engine torque, the engine rotational number or shift position, wheel rotational numbers as calculated from the wheel speeds detected by the velocity detecting means, and a tire radius, and

wherein a magnitude of force acting on the driving wheels is  
5 obtained from the driving force and the lateral directional acceleration.

According to a third aspect of the present invention, there is provided a program for alarming decrease in tire air-pressure wherein, for issuing an alarm of decrease in tire air-pressure of a vehicle, a computer is made to function as a judging means which judges decrease  
10 in tire air-pressure on the basis of wheel speeds detected by velocity detecting means, and a threshold changing means which changes respective thresholds for determining whether judgment of decrease in tire air-pressure is to be made or not depending on magnitude of driving torque of the vehicle when the vehicle is performing turning movements.

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#### BRIEF DESCRIPTION OF THE DRAWINGS

Fig. 1 is a block diagram illustrating one embodiment of the apparatus for alarming decrease in tire air-pressure according to the present invention;

20 Fig. 2 is a block diagram illustrating electric arrangements of the apparatus for alarming decrease in tire air-pressure of Fig. 1;

Fig. 3 is a graph for illustrating a region  $D_1$  in which no judgment of decrease in tire air-pressure is performed according to one embodiment of the method for alarming decrease in tire air-pressure of  
25 the present invention; and

Fig. 4 is a graph for illustrating a region  $D_2$  in which no judgment of decrease in tire air-pressure is performed according to one

embodiment of the method for alarming decrease in tire air-pressure of the present invention.

### DETAILED DESCRIPTION

5           The method and apparatus for alarming decrease in tire air-pressure and the program for alarming decrease in tire air-pressure according to the present invention will now be explained in details while referring to the drawings.

          As illustrated in Figs. 1 and 2, the apparatus for detecting  
10   decrease in tire air-pressure according to one embodiment of the present invention is for judging whether air-pressure of either of four tires  $W_1$ ,  $W_2$ ,  $W_3$  and  $W_4$  provided in a four-wheeled vehicle is decreased or not, and includes ordinary wheel speed sensors 1 respectively provided in relation to the respective tires  $W_1$ ,  $W_2$ ,  $W_3$  and  $W_4$ . Outputs of the wheel  
15   speed sensors 1 are supplied to a control unit 2. An alarm display 3 composed of liquid crystal elements, plasma display elements or CRT for informing a tire  $W_i$  of which the tire air-pressure has decreased, and an initialization switch 4 which might be operated by a driver are connected to the control unit 2.

20           The control unit 2 includes an I/O interface 2a required for sending/receiving signals to/from an external device, a CPU 2b which functions as a center of calculation, a ROM 2c which stores a control operation program for the CPU 2b, and a RAM 2d into which data are temporally written and are read out therefrom when the CPU 2b  
25   performs control operations.

          Pulse signals corresponding to the rotational number of the tire  $W_i$  (hereinafter referred to as "wheel speed pulse") are output from

the wheel speed sensors 1. In the CPU 2b, wheel rotational numbers  $N_w$  for the respective tires  $W_i$  are calculated on the basis of the wheel speed pulses as output from the wheel speed sensors at specified sampling periods  $\Delta T$  (sec), for instance,  $\Delta T = 1$ .

5            Though not illustrated, an engine torque detecting means such as a conventionally known torque sensor is provided for detecting an engine torque  $T_E$ .

            Further, though not illustrated, an conventionally known engine rotational number detecting means is provided for detecting an  
10 engine rotational number  $N_E$ , and a lateral directional acceleration detecting means such as a conventionally known G sensor is provided for detecting a lateral directional acceleration  $A_L$  (so-called lateral G).

            While the force applying on the driving wheel tires is composed of a sum of driving force in front and rear directions and  
15 turning force in lateral directions (cornering force), the driving force in front and rear directions can be obtained as a driving force applied onto one wheel from the engine torque information obtained from the engine, and the turning force can be obtained from the lateral G and a weight of a driving shaft. Representing a relationship of these by means of an  
20 equation, it would be

$$\begin{aligned} & (\text{sum } F_{\text{sum}} \text{ of force acting on the driving wheel tires})^2 \\ & = \text{driving force } F_D^2 + \text{turning force } F_T^2 (\geq (\text{threshold } F_\theta)^2) \end{aligned} \tag{3}$$

25

and the graph as illustrated in Fig. 3 can be obtained.

Here,



$$\begin{aligned} \text{Driving force } F_D(N) &= \text{engine torque } T_E(Nm) \times \\ &(\text{engine rotational number } N_E \div \text{wheel rotational number } N_W) \div \\ &\text{tire radius } R_T(m) \div \text{driving wheel number } n \end{aligned} \quad (4)$$

5                      Turning force  $F_T(N) =$   
                         lateral directional acceleration  $A_L(m/sec^2) \times$   
                         driving wheel shaft weight  $W_D(kg)$  (5)

In this respect, the engine torque  $T_E$  can also be obtained  
10 from an engine control unit through a communication line such as a  
CAN (car-mounted network) besides the above-described, and the value  
of (engine rotational number  $N_E \div$  wheel rotational number  $N_W$ ) can be  
obtained from a reduction ratio of a driving system or from a gear ratio of  
a transmission.

15                      Where the thus obtained sum  $F_{sum}$  acting on the tire is not  
more than the threshold  $F_\theta$ , judgment of decrease in tire air-pressure is  
performed. On the other hand, where the sum  $F_{sum}$  acting on the tire  
has exceeded the threshold  $F_\theta$ , no judgment of decrease in tire air-  
pressure is performed. More particularly, when the vehicle is in a  
20 condition of the hatched region  $D_1$  in Fig. 3 (that is, where sum  $F_{sum}$   
acting on the tire  $>$  threshold  $F_\theta$ ), no judgment of decrease in air-  
pressure shall be performed. With this arrangement, it is possible to  
improve the detection accuracy without issuing an erroneous alarm even  
in the case where a large driving force is applied when running on a  
25 climb road or when performing trailer towing.

The threshold  $F_\theta$  can be obtained through actual vehicle tests  
or on the basis of tire characteristic data ( $\mu$ -S, CF etc.) obtained through

bench tests.

The above-mentioned program for performing the method for alarming decrease in tire air-pressure might be stored, for instance, in the ROM 2c as illustrated in Fig. 1, and for issuing an alarm of decrease  
5 in tire air-pressure of the vehicle, the CPU 2b of the computer might be made to function as the judging means which judges decrease in tire air-pressure on the basis of wheel speeds detected by the velocity detecting means, and the threshold changing means which changes  
10 respective thresholds for determining whether judgment of decrease in tire air-pressure is to be made or not depending on the magnitude of driving torque of the vehicle when the vehicle is performing turning movements.

In this respect, it is difficult to exactly obtain the turning force  $F_T$ , and it is actually necessary to take a load shift during turning,  
15 a slip angle, or a structure of a suspension into consideration. Accordingly, in another embodiment of the present invention, it is possible to replace the turning force  $F_T$  by lateral directional acceleration  $A_L$  or to perform linear replacement. In this case, where

$$\begin{aligned} & | \text{driving force } F_D(N) + \text{coefficient } a \times \\ & \text{lateral directional acceleration } A_L(m/sec^2) | \geq \\ & \text{threshold } F_\theta \end{aligned} \quad (6)$$

is satisfied (that is, in a condition of the hatched region  $D_2$  in Fig. 2), no  
25 judgment of decrease in tire air-pressure is performed. Here, the driving force  $F_D$  and the lateral directional acceleration  $A_L$  can be obtained similar to the above-mentioned embodiment.

In this respect, this equation can be rewritten as

$$| \text{lateral directional acceleration } A_L(\text{m/sec}^2) | \geq (\text{threshold } F_\theta - \text{driving force } F_D(\text{N})) / \text{coefficient } a \quad (7)$$

5

This means, in other words, that the threshold  $F_\theta$  of the lateral directional acceleration  $A_L$  with which no judgment of decrease in air-pressure is performed is changed depending on the value of the driving force  $F_D$  of the engine. By performing such control, it is possible to  
10 improve the detection accuracy without issuing an erroneous alarm even in the case where a large driving force is applied when the vehicle is, for instance, running on a climbing road or when it performs trailer towing.

When the program for performing the method for alarming decrease in tire air-pressure is also stored in the ROM 2c as illustrated  
15 in Fig. 1, the CPU 2b of the computer might be made to function as the judging means which judges decrease in tire air-pressure on the basis of wheel speeds detected by the velocity detecting means, and the threshold changing means which changes respective thresholds for determining whether judgment of decrease in tire air-pressure is to be  
20 made or not depending on the magnitude of driving torque of the vehicle when the vehicle is performing turning movements for issuing an alarm of decrease in tire air-pressure of the vehicle.

The number of occurrences of an erroneous alarm were investigated by performing the embodiment according to the method for  
25 alarming decompression of tire of the present invention and by performing a Comparative Example according to a conventional method in which only turning correction is performed under the same conditions.

The test results are as shown in Table 1 below.

In this respect, the test conditions were such that the vehicle used was a passenger car of FF2400 cc, the used tires were 215/55R16 (summer tires manufactured by Sumitomo Rubber Industries, Ltd. (Trade name: LM702)), and tests were performed on a flat winding road and a climb winding road (gradient of 20 %), respectively, for performing the tests. Occurrences of an alarm were compared between cases in which all of the four wheel tires were at normal internal pressure and in which only the front left wheel was decompressed by 40 % when compared to normal internal pressure.

Table 1

	Flat Winding Road		Climb Winding Road (gradient of 20 %)	
	Normal Internal Pressure	Front Left Wheel (decompression by 40 %)	Normal Internal Pressure	Front Left Wheel (decompression by 40 %)
Example	No Alarm	Alarm (57 seconds)	No Alarm	Alarm (86 seconds)
Comparative Example	No Alarm	Alarm (57 seconds)	Alarm (erroneous) (320 seconds)	Alarm (72 seconds)

It can be understood from Table 1 that while an erroneous alarm is generated on the 20 % climb winding road on which a large driving force is applied to the driving wheels in the Comparative Example in which only turning correction is performed, no erroneous alarm is  
5 generated in the embodiment according to the method of the present invention.

According to the present invention, it is possible to improve the detection accuracy without issuing an erroneous alarm even in the case where a large driving force is applied when the vehicle is, for  
10 instance, running on a climbing road or when it performs trailer towing.